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[« Back to News](#)

### Portuguese Navy Acquires SeeByte's SeeTrack Military for use with GAVIA

SeeByte, the global leader in creating smart software for unmanned underwater vehicles, announces the sale of SeeTrack Military to the Portuguese Navy. The Portuguese Navy acquired SeeByte's leading SeeTrack Military software in order to plan, monitor, analyse and report on their GAVIA Autonomous Underwater Vehicle (AUV) operations.

"We here at SeeByte are proud to include the Portuguese Navy as one of our esteemed customers. We look forward to working closely with their Mine-counter Measures units and helping them make best use of SeeTrack Military as they carry out their important missions. SeeTrack military was designed to operate with multiple assets including diver hand-held systems, marine mammals, towed side-scan and all existing types of AUVs." said Ioseba Tena SeeByte's Sales Manager.

Lieutenant Commander Carlos Afonso (Head of PO Navy MW Department) stated: "SeeTrack Military is more than just mosaics. It is a software that allows us to run our AUV operations, supporting all the mission life-cycle Planning, Execution, Analysis and Data Dissemination. Importantly, the SeeByte software provides functionalities not easy to find as an all-in-one software; the output products coming from SeeTrack increase the interoperability of our MCM Teams with MCM International Community. Our GAVIA systems are currently unique in the international MCM community and with SeeTrack Military we are able to deliver outputs useful to the wider NATO community."

SeeTrack Military has become the de facto standard smart technology for the worldwide defence market. Showcased in a multitude of military situations, this product is currently used by Navy teams in missions to search identify and recover man-made underwater objects and to enhance the capabilities of their remote vehicles, marine mammals and divers. As a result, our customers are saving time, money and valuable man-hours while reducing unnecessary risk for the human operators who eventually have to interface with the underwater objects.