




# SeeTrack

## Multi Domain Command and Control

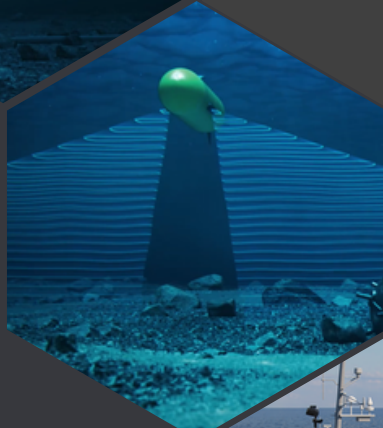






SeeTrack is SeeByte's internationally proven multi-domain, command and control system for Robotic and Autonomous Systems (RAS).

SeeTrack provides mission planning, monitoring (situational awareness) and data analysis for single or multi-vehicle operations.

As a vendor-neutral solution, SeeTrack has been integrated with numerous world leading Robotic and Autonomous Systems. SeeTrack ensures the end-user learns a single way of working, with a common user interface, and suite of tools to operate multiple assets.



*Supports multi-nation joint operations and is in service with over 20 navies worldwide*

- 
- 
-  **Supports World Leading RAS**
  -  **Supports Multi-Nation Joint Operations**
  -  **Rapid, Multi-Sensor Data Fusion**
  -  **Commercially Controlled Open Architecture**
  -  **Comprehensive Software Development Kit**

**seebyte**

A BATTELLE COMPANY

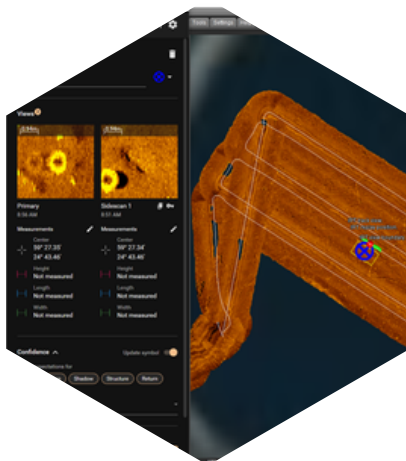
# SeeTrack

## Interchangeability

SeeTrack can support multi-nation operations by enabling vehicles and payloads to be upgraded or replaced without impact to operator workflow, or need for operator re-training. Urgent operational requirements can be added quickly to address emergent threats or conduct a unique mission set.

## Data Analysis

SeeTrack is designed to handle large volumes of high-resolution data from multiple sensors. Mission review capabilities include; target picking using the waterfall sonar review, sensor mosaic tools, and custom report generation.



## Campaign Manager

SeeTrack manages all data from current and previous events, with detailed mission plans, sensor data, and contact reporting. Search through mission history, perform change detection, and generate reports.

## Additional tools



Mission Level  
Autonomy



ATR  
System



Whitepapers

For more information please contact our team at  
+44 (0) 131 447 4200 or [sales@seebyte.com](mailto:sales@seebyte.com)

## Specifications

### Supported Platforms

- Artemis (Blueprint Subsea)
- Bluefin Robotics (GDMS)
- Gavia (Teledyne)
- Iver 2/Iver 3 (L3 Harris)
- LAUV (OceanScan-MST)
- Navigator (Shark Marine Technologies)
- REMUS (HII)

### Side Scan Sonar Formats

- EdgeTech
- Klein (MIND-Technology)
- Kraken MINSAS and KATFISH
- Marine Sonic Technology
- Sonardyne Solstice

### Forward Look Sonar Formats

- Teledyne BlueView
- Tritech Gemini

### Video Formats

- Voyis
- MPG and others assuming operating systems CODEC availability

### Primary Support Raster and Vector Formats

- S-57 ENC
- S-63 Encrypted ENC
- ESRI Shape files
- GeoTIFF

### Recommended System Requirements

- Operating System: Windows 11
- Intel i7 processor (generation 10)
- Solid State Drive (SSD)
- 1 TB free disk drive space
- 32 GB RAM
- Graphics card: Nvidia GPU 8GB RAM
- Internet connection recommended, but not essential
- Windows installed using English language and US/UK locale
- Web browser + PDF viewer

This is not an exhaustive list of supported formats. For the latest specifications please contact us.